

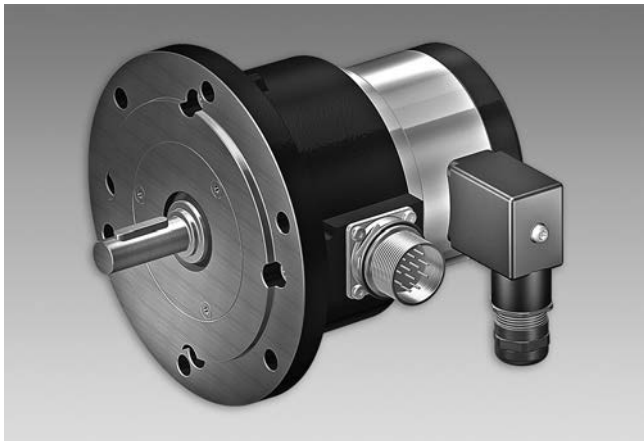
Combination

Encoder and tachogenerator in combination

Solid shaft with EURO flange B10

100...5000 pulses per revolution

FOG 9 + GT 7



FOG 9 + GT 7

Features

- Compact, robust die-cast housing
- Flange connector with metal mating connector
- EURO flange B10, solid shaft $\varnothing 11$ mm
- Temperature compensation of tacho voltage as standard
- Open circuit voltage 10...60 mV per rpm

Optional

- Connecting cable
- Function control with EMS (Enhanced Monitoring System)

Technical data - electrical ratings (tachogenerator)

Reversal tolerance	≤ 0.1 %
Linearity tolerance	≤ 0.15 %
Temperature coefficient	± 0.05 %/K (open-circuit)
Isolation class	B
Calibration tolerance	± 5 %
Climatic test	Humid heat, constant (IEC 60068-2-3, Ca)
Armature-circuit time-constant	< 4 μ s

FOG 9 + GT 7.08

Performance	0.3 W (speed ≥ 5000 rpm)
Open-circuit voltage	10...30 mV per rpm

FOG 9 + GT 7.16

Performance	0.6 W (speed ≥ 5000 rpm)
Open-circuit voltage	40...60 mV per rpm

Technical data - electrical ratings (encoder)

Voltage supply	9...30 VDC; 5 VDC ± 5 %
Consumption w/o load	≤ 100 mA
Pulses per revolution	100...5000
Phase shift	$90^\circ \pm 20^\circ$
Scan ratio	40...60 %
Reference signal	Zero pulse, width 90°
Output frequency	≤ 120 kHz ≤ 300 kHz (on request)
Output signals	K1, K2, K0 + inverted Error output (only EMS)
Output stages	HTL; TTL/RS422

Technical data - mechanical design

Size (flange)	$\varnothing 115$ mm
Shaft type	$\varnothing 11$ mm solid shaft
Admitted shaft load	≤ 200 N axial ≤ 300 N radial
Flange	EURO flange B10
Protection DIN EN 60529	IP 55
Operating speed	≤ 10000 rpm
Operating torque typ.	6 Ncm
Rotor moment of inertia	160 gcm ²
Materials	Housing: aluminium die-cast Shaft: stainless steel
Operating temperature	-30...+100 °C -25...+100 °C (> 3072 pulses per revolution)
Resistance	IEC 60068-2-6 Vibration 10 g, 10-2000 Hz IEC 60068-2-27 Shock 100 g, 6 ms
Connection	Flange connector M23, 12-pin Screw terminal connector Connecting cable (option)
Interference immunity	EN 61000-6-2
Emitted interference	EN 61000-6-3
Approval	CE

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Weight approx.	1.3 kg
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FOG 9 + GT 7.16

Weight approx.	1.6 kg
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Part number

Incremental encoder with tachogenerator

FOG9 **DN** **+ GT7.08L/4**

Open-circuit voltage
 10 10 mV per rpm
 20 20 mV per rpm
 30 30 mV per rpm

Voltage supply / signals
 I 9...30 VDC / output stage HTL with inverted signals
 TTL 5 VDC / output stage TTL with inverted signals
 R 9...30 VDC / output stage TTL with inverted signals

Pulse number - see table

Output signals
 DN K1, K2, K0

EMS - Enhanced Monitoring System

Without EMS

.2 With EMS

Pulse number

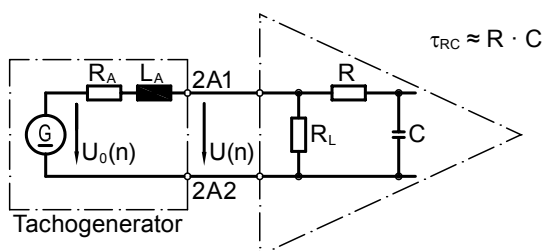
100	200	400	900	2048
120	250	500	1000	2500
128	256	512	1024	3072
180	300	600	1200	4096
192	360	720	1250	5000

Other pulse numbers on request.

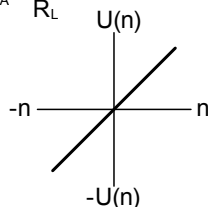
Data according to type

Type	Off-load voltage	Minimum load required depending on speed range [rpm]			Maximum operating speed	Armature resistance	Armature inductance
		0-3000	0-6000	0-n _{max}			
	U ₀ [mV/rpm]	R _L [kΩ]	R _L [kΩ]	R _L [kΩ]	n _{max} [rpm]	R _A (20°C) [Ω]	L _A [mH]
GT7.08L/410	10	≥5	≥12	≥27	9000	60	20
GT7.08L/420	20	≥20	≥48	≥108	9000	230	80
GT7.08L/430	30	≥45	≥108	≥243	9000	550	180
Superimposed ripple (for τ _{RC} = 0.3 ms):		≤0.6% (peak-peak)			≤0.25% (rms)		

Replacement switching diagram



$$\tau_A \approx \frac{L_A}{R_L}$$



Polarity for positive rotating direction:

2A1: + (VDE)
 2A2: -

$$U(n) = U_0(n) \frac{R_L}{R_A + R_L} \approx U_0(n) \text{ for } R > R_L \gg R_A$$

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Incremental encoder with tachogenerator

FOG9 DN + GT7.16L/4

Open-circuit voltage
40 40 mV per rpm
60 60 mV per rpm

Voltage supply / signals
I 9...30 VDC / output stage HTL with inverted signals
TTL 5 VDC / output stage TTL with inverted signals
R 9...30 VDC / output stage TTL with inverted signals

Pulse number - see table

Output signals
DN K1, K2, K0

EMS - Enhanced Monitoring System
Without EMS

.2 With EMS

Pulse number

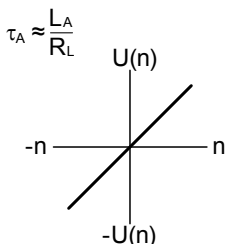
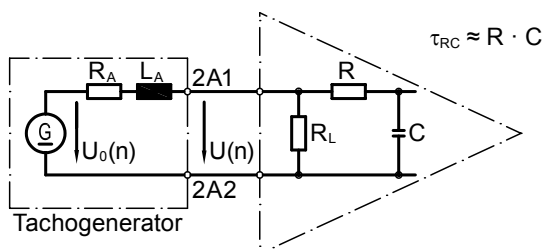
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	U ₀ [mV/rpm]	R _L [kΩ]	R _L [kΩ]	R _L [kΩ]	n _{max} [rpm]	R _A (20°C) [Ω]	L _A [mH]
GT7.16L/440	40	≥40	≥96	≥216	9000	410	160
GT7.16L/460	60	≥90	≥215	≥223	6100	760	360
Superimposed ripple (for τ _{RC} = 0.3 ms):		≤0.6% (peak-peak)			≤0.25% (rms)		

Replacement switching diagram



Polarity for positive rotating direction:

2A1: + (VDE)
2A2: -

$$U(n) = U_0(n) \frac{R_L}{R_A + R_L} \approx U_0(n) \text{ for } R > R_L \gg R_A$$

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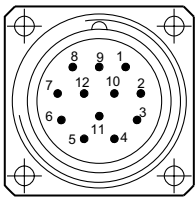
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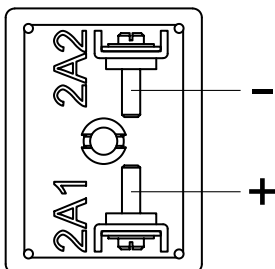
Terminal assignment

View A		Connecting cable assignment
Flange connector M23 FOG 9, 12 pin, male contacts, CW		
Pin	Assignment	Cable colour
1	$\overline{K2}$ (K2 inv.)	Yellow
2	Do not use	---
3	K0 (Zero pulse)	Grey
4	$\overline{K0}$ (Zero pulse inv.)	Pink
5	K1	White
6	$\overline{K1}$ (K1 inv.)	Brown
7	Do not use (Option EMS: \overline{Err})	---
8	K2	Green
9	Do not use (Option EMS: 0 V)	---
10	0 V	Blue
11	Do not use	---
12	+UB	Red



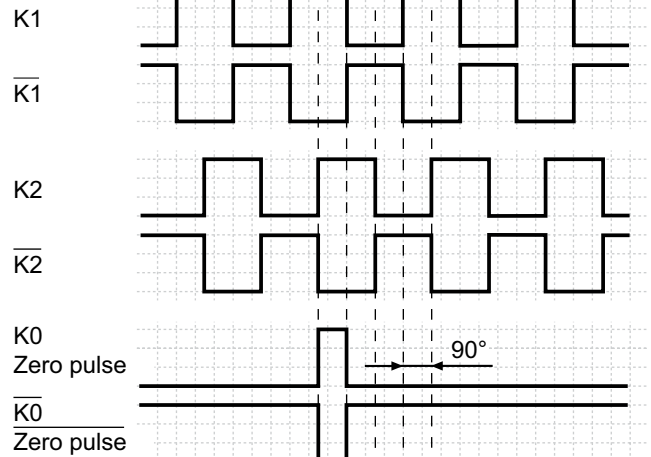
View A - Connecting terminal GT 7

Polarity for positive rotating direction



Output signals

At positive rotating direction



Option EMS: LED status / Error output

Flash light red*	Error of signal sequence, zero pulse or pulses (Error output = HIGH-LOW alternation)
Red	Overload output driver (Error output = LOW)
Flash light green	Encoder o.k., rotating (Error output = HIGH)
Green	Encoder o.k., stopped (Error output = HIGH)
No light	No output voltage connection or wrong connection (Error output = LOW)

* Only at rotating encoder

Accessories

Connectors and cables

HEK 8 Sensor cable for encoders

Mounting accessories

K 35 Spring washer coupling for solid shaft $\varnothing 6...12$ mm

K 50 Spring washer coupling for solid shaft $\varnothing 11...16$ mm

K 60 Spring washer coupling for solid shaft $\varnothing 11...22$ mm

Diagnostic accessories

HENQ 1100 Analyzer for encoders

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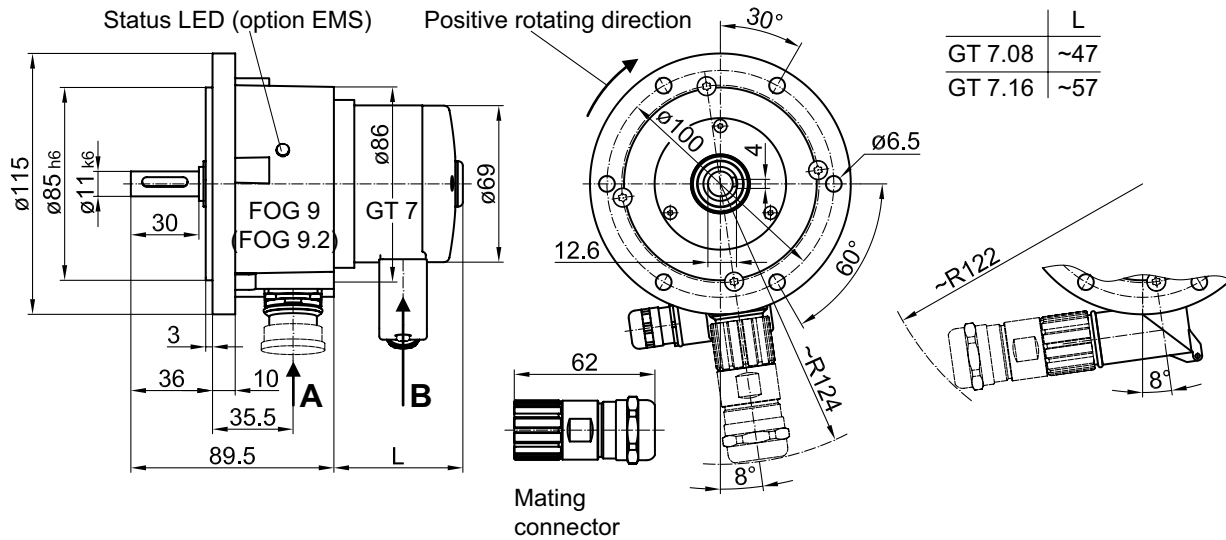
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Dimensions

FOG 9 + GT 7 (FOG 9.2 + GT 7) - Version with flange connector



FOG 9 + GT 7 - Version with connecting cable

