

# Encoders without bearings - incremental

Sensor head with magnetic tape for shaft  $\varnothing 300\text{...}3183$  mm

512...131072 pulses or 512...16384 sinewave cycles per turn

## MIR 3000F - HDmag flex



### Features

- Bearingless incremental encoder with magnetic sensing
- Flexible design for wide shaft diameter range
- Square-wave signals HTL/TTL or sine signals
- Max. 131072 pulses per revolution
- Status indication via system OK output and LED
- Robust and wearless
- Fully encapsulated electronics IP 67
- Large mounting tolerances

### Technical data - electrical ratings

Voltage supply	4.75...30 VDC
Consumption w/o load	$\leq 300$ mA (24 VDC)
Sensing method	Magnetic
Output signals	A+, B+, R+, A-, B-, R-
Initializing time	$\leq 1000$ ms after power on
Status indicator	Color-LED, system OK output
Interference immunity	EN 61000-6-2
Emitted interference	EN 61000-6-3
Approval	CE

### Technical data - electrical ratings (square-wave)

Pulses per revolution	512...131072
Phase shift	$90^\circ \pm 2^\circ$
Scan ratio	45...55 %
Reference signal	Zero pulse, width $90^\circ$
Output frequency	$\leq 500$ kHz (HTL) $\leq 2$ MHz (TTL)
Output stages	HTL TTL/RS422

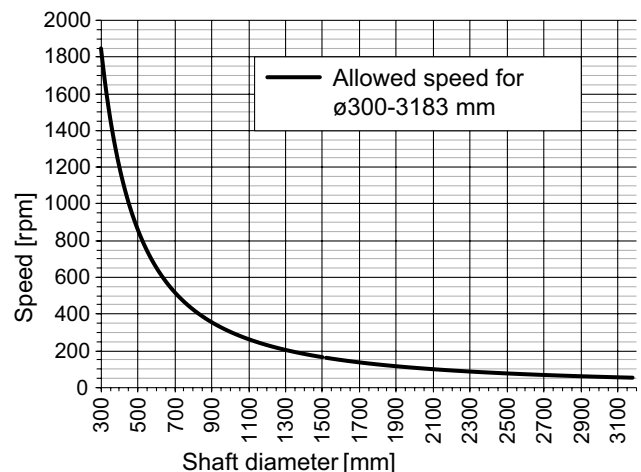
### Technical data - electrical ratings (SinCos)

Sinewave cycles per turn	512...16384
Phase shift	$90^\circ \pm 2^\circ$
Reference signal	Zero pulse, width $360^\circ$
Output frequency	$\leq 500$ kHz
Output stages	SinCos 1 Vpp

### Technical data - mechanical design

Dimensions (sensor head)	165 x 25 x 93 mm
Shaft type	$\varnothing 300\text{...}3183$ mm (through hollow shaft)
Axial tolerance	$\pm 5$ mm (belt to head)
Radial tolerance	1...3 mm (belt to head)
Protection DIN EN 60529	IP 67
Operating temperature	$-40\text{...}+85$ °C
Operating speed	$\leq 1850$ rpm ( $\varnothing 300$ mm) $\leq 150$ rpm ( $\varnothing 1500$ mm) see diagram below
Resistance	IEC 60068-2-6 Vibration 30 g, 10-2000 Hz IEC 60068-2-27 Shock 300 g, 6 ms
Connection	Flange connector M23, 12-pin
Weight approx.	730 g (head), 120 g (belt/m), 17 g (lock)

### Speed dependent on the shaft diameter



# Encoders without bearings - incremental

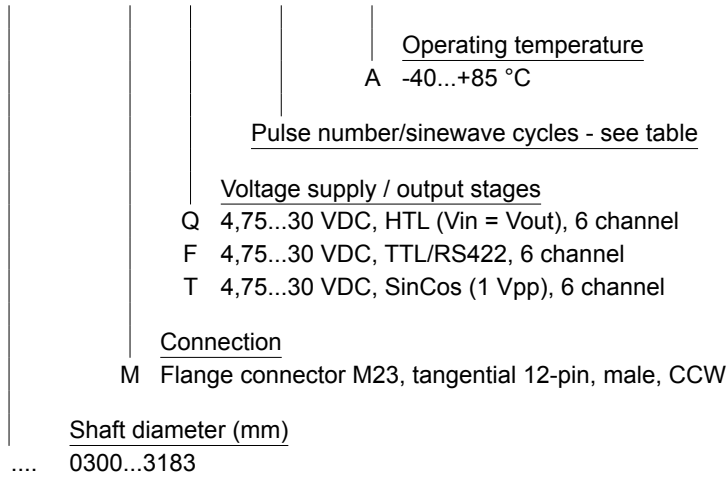
Sensor head with magnetic tape for shaft  $\varnothing$ 300...3183 mm  
512...131072 pulses or 512...16384 sinewave cycles per turn

MIR 3000F - HDmag flex

## Part number

MIR3000F- 

....	.	M	.	.	.	A
------	---	---	---	---	---	---



## Pulse number/sinewave cycles

512	1024	5000	16384
720	2048	8192	32768
1000	4096	10000	131072

Other pulse numbers/sinewave cycles on request.  
Maximum sinewave cycles 16384 for SinCos output.

## Accessories

### Connectors and cables

HEK 8	Sensor cable for encoders
11068549	Mating connector M23, solder version, 12-pin, CW

# Encoders without bearings - incremental

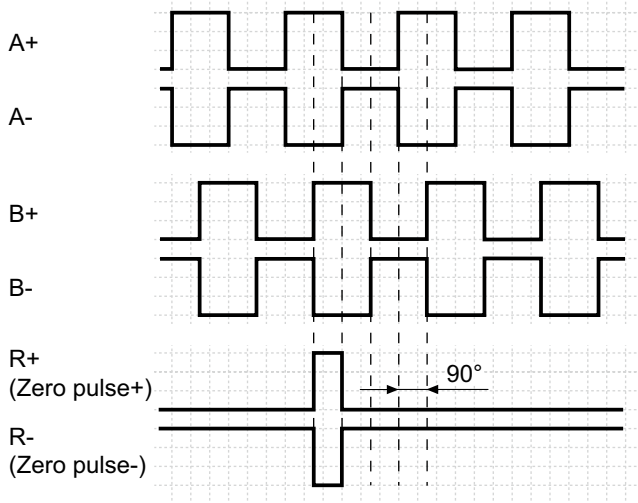
Sensor head with magnetic tape for shaft  $\varnothing 300...3183$  mm

512...131072 pulses or 512...16384 sinewave cycles per turn

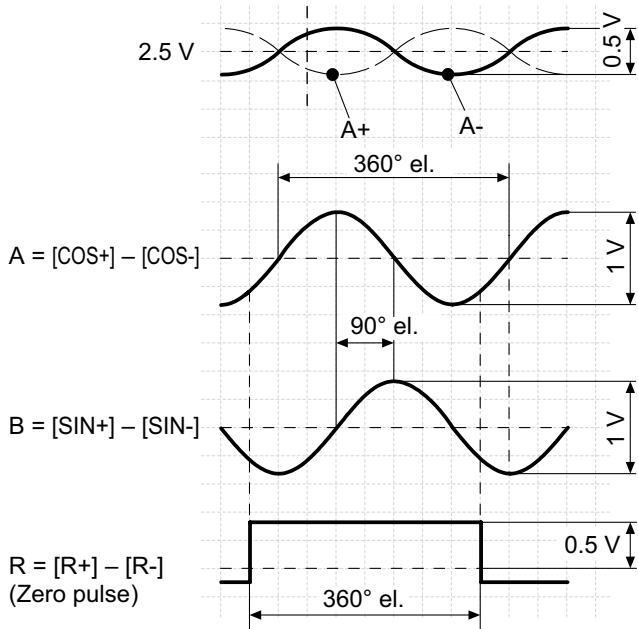
## MIR 3000F - HDmag flex

### Output signals

Version with square-wave signals HTL oder TTL at positive rotating direction



Version with sinewave signals at positive rotating direction



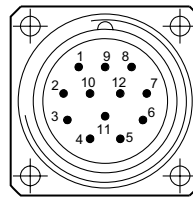
### Terminal assignment

#### View A

Flange connector M23, 12-pin, male contacts, CCW

Pin	Assignment
1	B- / SIN-
2	System OK-
3	R+ (Zero pulse)
4	R- (Zero pulse inv.)
5	A+ / COS+
6	A- / COS-
7	Do not use
8	B+ / SIN+
9	Do not use
10	0 V
11	System OK+
12	+UB

No error if „System OK“ output = HIGH



# Encoders without bearings - incremental

Sensor head with magnetic tape for shaft  $\varnothing 300 \dots 3183$  mm  
 512...131072 pulses or 512...16384 sinewave cycles per turn

MIR 3000F - HDmag flex

## Dimensions

