

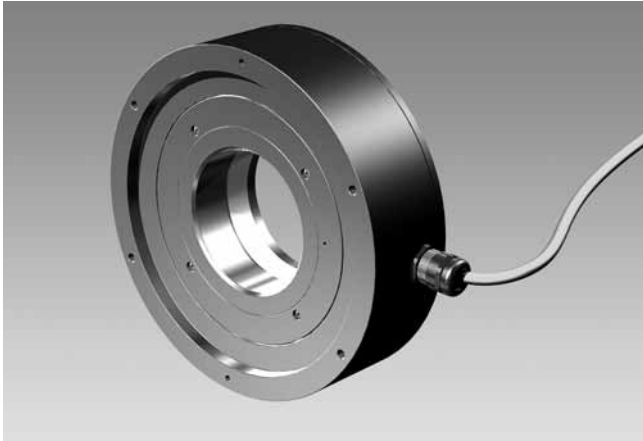
# Encoders without bearings - incremental

Incremental encoder with optical sensing

Through hollow shaft  $\varnothing 85...95$  mm

2500 pulses per revolution

HG 21, HG 211



HG 211

## Technical data - electrical ratings

Voltage supply	9...26 VDC 5 VDC $\pm 5$ %
Consumption w/o load	< 100 mA
Sensing method	Optical
Pulses per revolution	2500
Output stages	HTL TTL/RS422
Output signals	K1, K2, K0 + inverted
Reference signal	Zero pulse, width 90°
Output frequency	$\leq 120$ kHz $\leq 160$ kHz (Option)
Phase shift	90° $\pm 20$ °
Scan ratio	40...60 %
Interference immunity	EN 61000-6-2
Emitted interference	EN 61000-6-3
Approvals	CE, RoHS, UL approval / E256710

## Features

- Large axial and radial displacement of the shaft permitted
- Fit for high operating speed
- Robust and wearless
- 2500 pulses per revolution
- Logic level TTL with regulator UB 9...26 VDC

## Optional

- Redundant sensing (version M)

## Technical data - mechanical design

Axial tolerance	-0.5...1.5 mm (with zero pulse) -0.5...2.5 mm (without zero pulse)
Radial tolerance	$\pm 0.05$ mm (with zero pulse) $\pm 0.2$ mm (without zero pulse)
Shaft type	$\varnothing 85...95$ mm (through hollow shaft)
Protection DIN EN 60529	IP 44
Operating temperature	-30...+70 °C
Operating speed	$\leq 12000$ rpm
Resistance	IEC 60068-2-6 Vibration 10 g, 10-2000 Hz IEC 60068-2-27 Shock 100 g, 6 ms
Materials	Housing: aluminium Shaft: stainless steel
Connection	Cable with mating connector, 12-pin (2x with option M)
Weight approx.	5.8 kg

## HG 21

Size (flange)	$\varnothing 240$ mm
Rotor moment of inertia	43 kgcm <sup>2</sup>

## HG 211

Size (flange)	$\varnothing 210$ mm
Rotor moment of inertia	52 kgcm <sup>2</sup> ( $\varnothing 95$ )

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## Part number

HG 21    **2500**

HG 211    **2500**

Voltage supply / signals

- 9...26 VDC / output circuit HTL
- CI 9...26 VDC / output circuit HTL (C) with inverted signals
- TTL 5 VDC / output circuit TTL with inverted signals
- R 9...26 VDC / output circuit TTL with inverted signals (for output signals DN)

Output signals

- D K1, K2
- DN K1, K2, K0

Redundant sensing

- Without redundant sensing
- M With redundant sensing

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- Without redundant sensing
- M With redundant sensing

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Incremental encoder with optical sensing

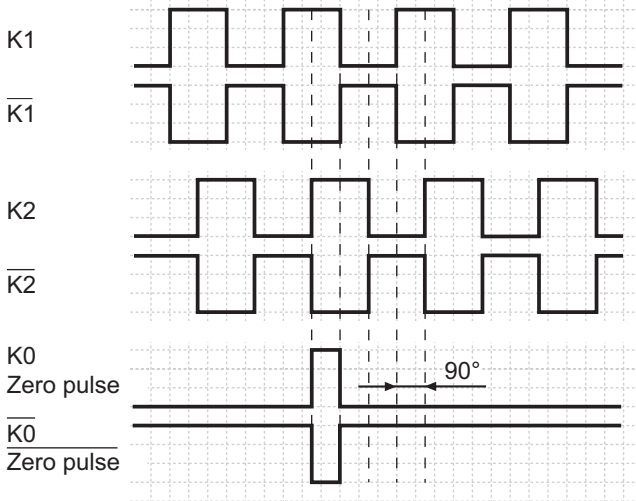
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2500 pulses per revolution

HG 21, HG 211

## Output signals

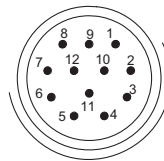
At positive rotating direction



## Terminal assignment

View A - Mating connector, 12 pin, male contacts, CW

Pin	Assignment
1	$\overline{K2}$ (K2 inv.)
2	Do not use
3	K0 (Zero pulse)
4	$\overline{K0}$ (Zero pulse inv.)
5	K1
6	$\overline{K1}$ (K1 inv.)
7	Do not use
8	K2
9	Do not use
10	0 V
11	Do not use
12	+UB



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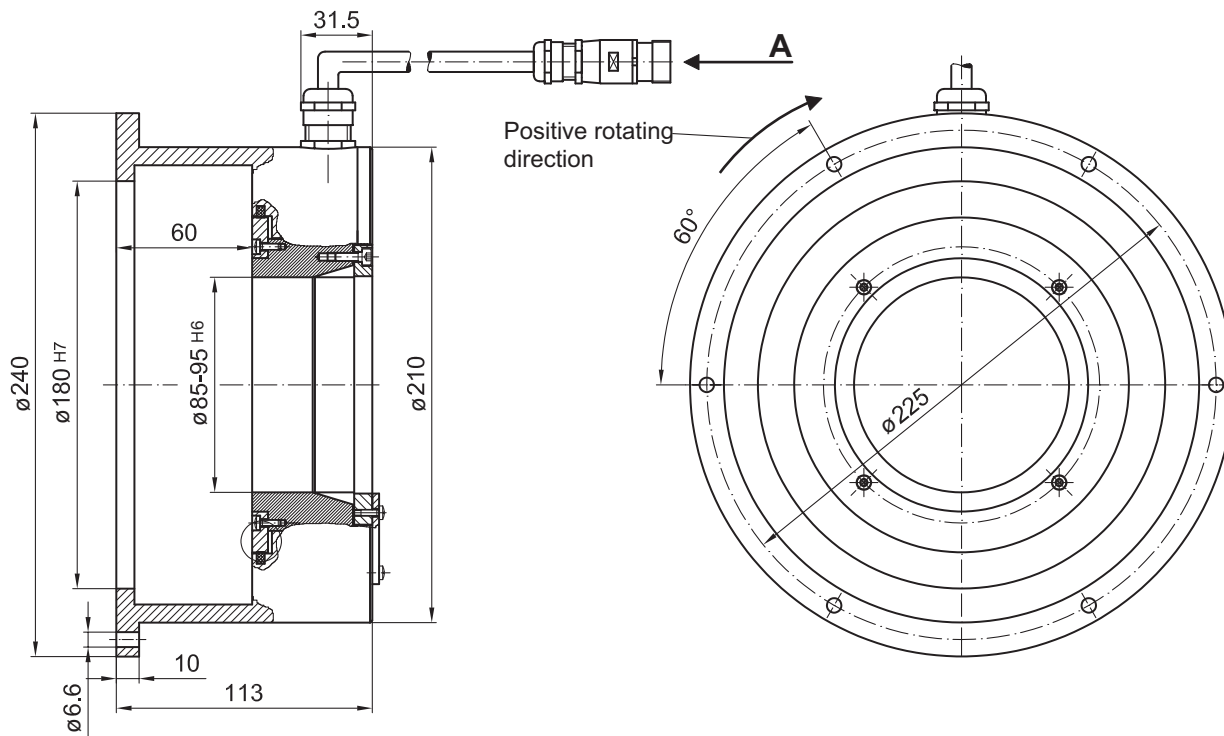
Through hollow shaft  $\varnothing 85\text{--}95$  mm

2500 pulses per revolution

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## Dimensions

### HG 21



### HG 211

