

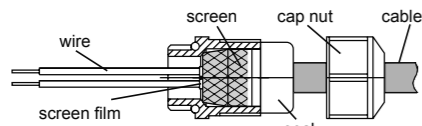
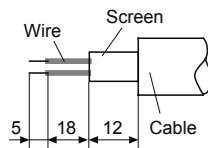
GB Assembly Instructions

**GBAMW, GBLMW, GBMMW
GCAMW, GCMW
GXAMW, GXLW, GXMMW
GEMMW**

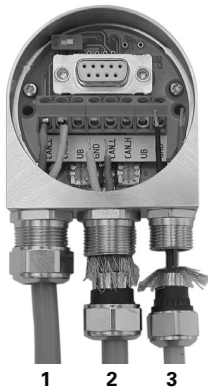
Absolute Encoder – SAEJ1939 9-16

Assignment – cable gland (bus cover)

- Unscrew cap nut of cable gland. Push cap nut and seal insertion onto the cable coat.
- Strip isolation of cable coat and cores and cut shielding foil, if any (picture).
- Bend the braided shield for about 90°.
- Push seal insertion to the braided shield. Insert seal and cable flush into the cable gland. Secure by carefully tightening the cap nut.



- Use cable gland no. 3 for supply only. Cable glands no. 1 and 2 are for optional use as bus lines. Consider the permitted cable cross-section.
- Use the shortest way to insert the cores into the terminals and mind the maximum core cross-section. Use core tip sleeves with flexible cores.
- There must not be any crossing of data lines with lines for power supply.
- Any cable gland not used has to be sealed by blind plug (included into delivery). The cap nut must be firmly tightened.



Danger
Warnings of possible danger.



General instructions
Information on appropriate product handling.



General remarks

Additional information

The installation instruction is supplementary to already existing documentation (e.g. catalog, data sheet, manual).



It is imperative to read the manual carefully prior to starting the device.

Appropriate use

- The encoder is a precision measuring device. It is explicitly designed for registration of angular positions and revolutions as well as evaluation and supply of measuring values as electric output signals for the subsequently connected device. The encoder must not be used for any other purpose.

Start up

- Installation and assembly of the encoder only by electrically skilled and qualified personnel.
- Consider also the operation manual of the machine manufacturer.

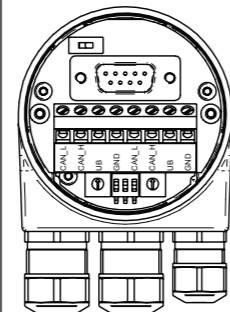


Safety instructions

- All electrical connections are to be revised prior to starting the system.
- Incorrect assembly and electrical connections or any other inappropriate work at encoder and system may lead to malfunction or failure of the encoder.
- Any risk of personal injury, damage of the system or company equipment due to failure or malfunction of the encoder has to be eliminated by corresponding safety measures.
- Do not operate encoder beyond the limit values stated in the data sheet.



Any disregard may lead to malfunctions, material damage and personal injury.



Locking torque
Terminal strip/screwing terminal max. 0.4 Nm
(recommended locking torque 0.3 Nm)
Connection bus cover max. 0.9 Nm

Core cross-section

| | |
|----------------------|--|
| Single wire (rigid) | Max. 1.5 mm ² |
| Fine wire (flexible) | Max. 1.0 mm ² |
| Fine wire (flexible) | With ferrule max. 0.75 mm ² |

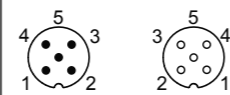
Cable diameter

| | |
|------------------|--|
| Cable gland 1, 2 | ø8...10 mm (-40...+85 °C) ø5...9 mm (-25...+85 °C) |
| Cable gland 3 | ø4.5...6 mm (-40...+85 °C) ø3...6 mm (-25...+85 °C) |

Terminal assignment (bus cover)

| | | |
|-------|-------|----------------------------------|
| Pin 1 | GND | Ground connection relating to UB |
| Pin 2 | UB | Supply voltage 10...30 VDC |
| Pin 3 | - | - |
| Pin 4 | CAN_H | CAN bus signal (dominant High) |
| Pin 5 | CAN_L | CAN bus signal (dominant Low) |

Terminals of the same significance are internally connected and identical in their functions. Max. load on the internal terminal connections UB-UB and GND-GND is 1 A each.



M12 connector (male/female)

Assignment – M12 connector

- Follow also the instructions of the respective supplier.
- Press mating connector softly into the plug.
- Turn mating connector carefully until the code mark is interlocking the corresponding space provided by the plug. Insert bushing completely. Tighten the nut as far as possible.



An optimized connection between encoder case and the braided shield of the connection cable is only achieved by the braided shield being placed generously onto the connector and the nut being secured firmly.

Disposal

Encoder components are to be disposed of according to the regulations prevailing in the respective country.



Transport and storing

- In original packing only.
- Do not drop or expose encoder to major shocks.



Assembly

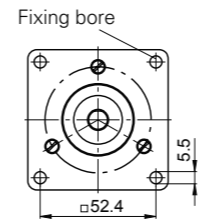
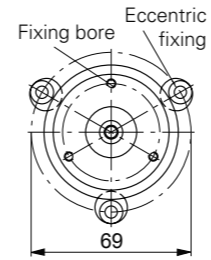
- Avoid punches or shocks on case and shaft.
- Avoid case distortion.
- Do not use any rigid links between encoder shaft and drive shaft.
- Do not open or modify encoder in any mechanical way.



Shaft, bearing, glass disc or electronic components might be damaged and a secure operation is no longer guaranteed.

Mechanical assembly

- Mount encoder using three screws using the three fixing bores of the flange. Consider the depth and diameter of the thread.
- Alternative mounting in any angular position is possible by means of three eccentric fixings (accessories).
- Use appropriate coupling to link drive shaft and encoder shaft. For appropriate links please refer to accessories.



The ends of the shafts must not touch each other. Any displacements due to temperature or mechanical tolerances have to be equalized by the coupling. Mind the maximum permitted axial or radial shaft load. Tighten fixing screws firmly.

Electrical installation

- Do not modify encoder in any electrical way and carry out any wiring work under power supply.
- Any electrical connection and plugging-on whilst under power supply is not permitted.
- A separate encoder supply has to be provided with consumers with high interference emission.

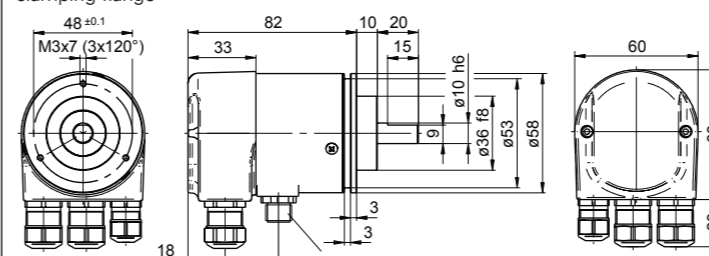
- Plug the bus cover carefully onto the D-SUB plug of the basic encoder, then push it over the rubber seal. Avoid the case getting wedged. The bus cover has to fit tightly the basic encoder.
- Tighten both fixing screws firmly and conformable.
- An optimized connection between encoder case and the braiding shield of the supply cable is only achieved by a complete and close fit of the bus cover onto the basic encoder (interlock).

Terminal assignment for models with additional incremental connector

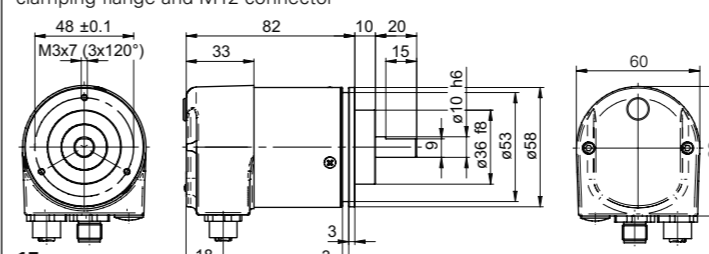
| | |
|-------|--------|
| Pin 1 | A |
| Pin 2 | B |
| Pin 3 | A inv. |
| Pin 4 | B inv. |
| Pin 5 | GND |

Dimensions

clamping flange

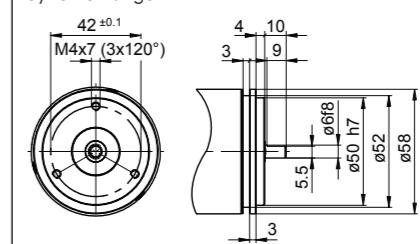


clamping flange and M12 connector

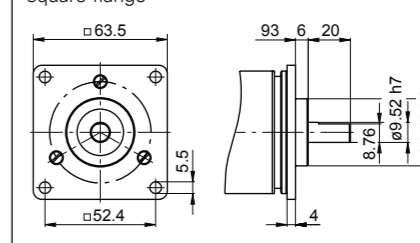


Dimensions

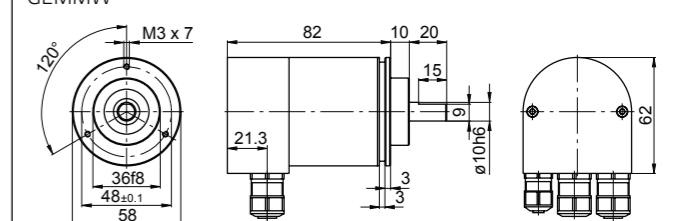
synchro flange



square flange



GEMMW



- Installation of the whole system has to be according to EMC standards. Installation environment as well as wiring have an impact on the encoder's EMC. Encoder and supplying lines are to be in separated locations or remote from lines with high interference emission (frequency transformers, protections, etc.).
- Encoder case and supply cable have to be completely screened.
- Ground (PE) encoder by using screened cables. The braided shield has to be connected to cable gland or plug. Grounding (PE) on both sides is recommended. Ground the case by the mechanical assembly, if latter is electrically isolated a second connection has to be provided. Ground cable screen by the subsequently connected devices. In case of ground loop problems at least grounding on one side is imperative.



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Electrical connection

- The bus cover is to be stored and transported whilst in the ESD bag only. The bus cover has to fit the case tightly and has to be firmly secured by screws.
- Unscrew both fixing screws of the bus cover.
- Loosen bus cover carefully and remove it in axial direction.



- For the last participant the terminators are to be switched "ON" by means of the 1-pin Dip switch (default OFF).
ON = final user
OFF = user X



The 3-pin Dip switch and the rotary switches have no function.