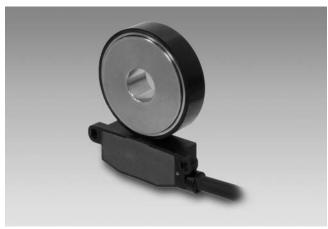
Subject to modification in technic and design. Errors and omissions exce

Encoders without bearings - incremental

Through hollow shaft ø8 to ø28 mm 64...2048 pulses per revolution

ITD49H00 - Rectangular signal



ITD49H00 - attachment variant adhesive mounting

Technical data - electrical ratings		
Voltage supply	5 VDC ±5 % 826 VDC	
Reverse polarity protection Yes		
Short-circuit proof	Yes	
Consumption w/o load	≤50 mA	
Pulses per revolution	642048	
Interpolation	1-fold (single), 2-fold, 4-fold, 8-fold, 16-fold, 32-fold	
Output signals	A 90° B + inverted A 90° B, N + inverted	
Output current	≤30 mA	
Output frequency	≤300 kHz (TTL) ≤160 kHz (HTL)	
System accuracy	±0.3°	
Output stages	TTL linedriver (short-circuit proof) HTL push-pull (short-circuit proof)	
Interference immunity	DIN EN 61000-6-2	
Emitted interference	DIN EN 61000-6-3	

Features

- Bearingless magnetic encoder
- Max. 2048 pulses per revolution
- Output circuits: HTL or TTL
- Fast, easy and space saving installation
- Maintenance-free
- High accuracy error max. ±0.3°
- Rotation speed max. 30000 rpm
- High resistance to dirt and vibrations

Optional

- Cable with connector
- Redundant sensing

Technical data - mechanical design		
Dimensions W x H x L	12 x 16 x 48 mm	
Shaft type	ø828 mm (through hollow shaft)	
Protection DIN EN 60529	IP 67 (relating to sealed electronics)	
Operating speed	≤30000 rpm	
Working distance	0.20.5 mm (radial), optimal 0,3 mm	
Axial offset	±0.5 mm	
Materials	Housing: plastic Shaft: stainless steel 1.4104	
Operating temperature	-40+100 °C (fixed cable)	
Resistance	DIN EN 60068-2-6 Vibration 10 g, 55-2000 Hz DIN EN 60068-2-27 Shock 100 g, 11 ms	
Weight approx.	250 g	
Connection	Cable 1 m	
Admitted cable length	15 m	

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ITD49H00 - Rectangular signal

Part	number

Pulse number - see table

Pulse number

64*	256	1024
128*	512	2048

^{*} Featured pulse numbers available as BI output signals.

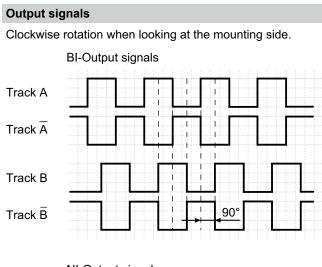


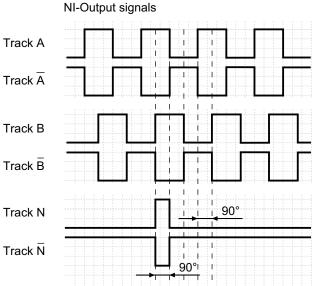
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Encoders without bearings - incremental

Through hollow shaft ø8 to ø28 mm 64...2048 pulses per revolution

ITD49H00 - Rectangular signal





	nals, cable [4x2x0,08 mm2]
Core colour	Assignment
green	Track A
yellow	Track A inv.
grey	Track B
pink	Track B inv.
red	UB
blue	GND
transparent	Shield/Housing
	nals, cable [4x2x0,08 mm2] Assignment
With NI-sign Core colour	nals, cable [4x2x0,08 mm2] Assignment
Core colour	Assignment
Core colour green	Assignment Track A
Core colour green yellow	Assignment Track A Track A inv.
Core colour green yellow grey	Assignment Track A Track A inv. Track B
Core colour green yellow grey pink	Assignment Track A Track A inv. Track B Track B inv.
Core colour green yellow grey pink brown	Assignment Track A Track A inv. Track B Track B inv. Track N
Core colour green yellow grey pink brown white	Assignment Track A Track A inv. Track B Track B inv. Track N Track N

Terminal assignment

Trigger level		
Outputs	Linedriver	
Output level High	≥2,5 V	
Output level Low	≤0,5 V	
Load	≤30 mA	

Outputs	Push-pull short-circuit proof
Output level High	≥UB -3 V
Output level Low	≤1,5 V
Load	≤30 mA



Encoders without bearings - incremental

Through hollow shaft Ø8 to Ø28 mm 64...2048 pulses per revolution

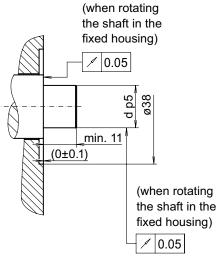
ITD49H00 - Rectangular signal

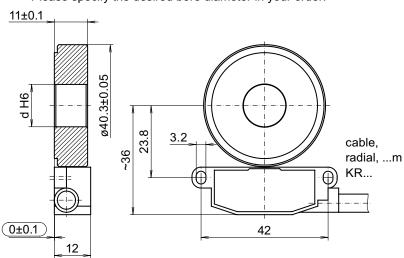
Dimensions

mounting side (proposition)

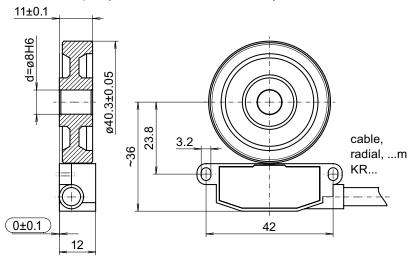
dimension drawing (optimal mounting)

d = \emptyset 9 mm, \emptyset 9.525 mm, \emptyset 10 mm, \emptyset 12 mm, \emptyset 12.7 mm, \emptyset 14 mm, \emptyset 15 mm, \emptyset 15.875 mm, \emptyset 19 mm, \emptyset 25 mm, \emptyset 25.4 mm, \emptyset 28 mm. Please specify the desired bore diameter in your order.





d = ø8 mm Please specify the desired bore diameter in your order.



Mounting type	Shaft tolerance	Requirement
Shrink fitting	d p5	Maximum heating of the pole wheel T _(max) =100 °C
Adhesive mounting	d g6	Please observe the manufacturer's instructions for the adhesive
		mounting with respect to adhesives and adhesive air gap.
		Recommendation: Adhesive Loctite 3504

Installation note:

The system, consisting of sensor and rotor, form a matched pair. They may not be exchanged individually. The sensor should be mounted on an electrically conductive surface on potting side.

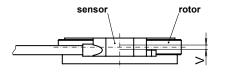


Encoders without bearings - incremental

Mounting tolerances, operating tolerances

Permitted change of position sensor to rotor during mounting and operation:

Axial offset:

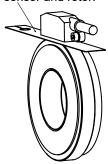


 $V = \pm 0.5$ mm, optimal 0.1 mm

Working distance:

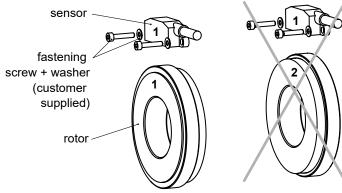
A = 0.2...0.5 mm, optimal 0.3 mm

Use the distance band as a mounting tool for optimal gap (0.3 mm) between sensor and rotor.



Mounting position

Mounting position (1-1) sensor to rotor should not be altered!



5